



MÁRIO RUIVO

Deep-sea Research Vessel





Deep-sea Research Vessel

| General | |
|---------------|---|
| Length | 75.6m |
| Beam | 14.8m |
| Draught | 5.8 m (4.5+1.3 from the gondola |
| Weight | 2290 Ton |
| Maximum speed | 11 knots |
| Service speed | ≤10 knots |
| Endurance | ≥30 days at sea without refueling |
| Accommodation | 47 (27 researchers and technicians and 20 crew members) |
| Safety | Complies with IMO, Lloyds Register and all national and international requirements |

| Propulsion & Generators | | |
|-------------------------|--|--|
| Engines | 2 X Ruston 8RKCM, 8V25.4, 1492 Kw (2000 Bhp) /900 rpm | |
| Bow Thrust | Engine: Mirrlees Blackstone, 6l22.2, 682 Kw (915 Bhp) / 1000 rpm Thrust Unit: Tees Gill Jet, Omni- Directional, 700 Kw | |
| Stern Thruster | Hundested Dk, 400 Kw | |
| Generators | 3 X Mirrlees Blackstone, 6l22.2, 400 Kw (Electric) / 900 rpm | |

| Navigation & Communication | | |
|----------------------------|--|--|
| Dynamic positioning | EMRI, DP1 | |
| GPS | 2 x Simrad MX510 1 x JRC-JLR 7700MKII | |
| Radar | 1 x Furuno FAR-2107 1 x Furuno FAR-2105 | |
| AIS | JRC-JHS-182 | |
| Navigation System | ECDIS 1: Transas 4000 ECDIS 2: Furuno PCU-3010 | |
| Gyro-Compass 1 | Raytheoon Anshutz STD | |
| Gyro-Compass 2 | Simrad MX510 | |
| Autopilot | Simrad AP70 | |
| Depth Measurement | Hondex HE-7300-DI | |
| Satellite phone | Sailor TT-3738A Sailor SC 4120 Iridium phone | |

Workboat

5.90 meters lenght and 1.92 meters width, fiberglass boat with center console, and 37 kW (50 Cv) motor.

Suitable for research activities, buoy maintenance, equipment deployment and recovery, and other marine activities.



Facilities

Dry laboratory with work benches.

Wet laboratory, with walk-in freezing tunnel, 570 Kg/cycle, -40°C final temperature, and walk-in freezer with 10 m³ total volume, -30°C conservation temperature, -18°C fish entry minimum temperature.

Workshop with lathe, pedestal drilling machine, turret milling machine, bench grinder, portable welding unit, oxi-acetylane welding/burning kit, workbench with vice, band saw.

Data processing room with 5 dedicated acoustic survey workstations and desk space for laptops.

Communal areas: lounge with TV and DVD players, gymnasium, sauna and cinema room.

Changing room with 16 lockers and toilet.

Hospital room with hospital bed and basic medical facilities.

| Deck Equipment | |
|---|--|
| A-frame, stern: HIDROFERSA SWL 16 ton | |
| A-frame, bow, SB: SWL 10 ton | |
| Cranes stern PT and SB: 2 x GUERRA M230.20A4, 1550 Kg – 11.7 m | |
| Crane, bow, SB: HEILA HLRM 140/4S SWL 8 | |
| Space on deck for 6 ship containers at the bow area | |
| 120 m ² of working area at the Stern | |
| Two side fixing poles to support scientific equipment on the port side. | |
| Two side arms (outriggers), 9 m in length, at the stern, for towing scientific equipment. | |

| Permanent Scientific Equipment | |
|--------------------------------|---|
| Motion reference system: | Kongsberg Seapath 380 |
| Net monitoring system: | Scanmar |
| Low frequency scanning sonar: | Kongsberg Simrad SX93 |
| Multi-beam echo sounder 1: | Kongsberg EM712, 0.5 x 1 degree, 2 to 2000 m depth |
| Multi-beam echo sounder 2: | Kongsberg EM304 MKII, 1 x 1 degree, full ocean depth |
| Split-beam echo sounder: | Simrad EK80 with ADCP (>400 m), 18, 38, 70, 120, 200 e 333 kHz. |
| Sub-bottom profiler: | Kongsberg TOPAS18, full ocean depth |
| Primary positioning: | Kongsberg Seapath 380 |
| Secondary positioning: | Applanix POSMV Occean Master |
| Sound velocity profiler: | Valeport miniSVS |

Winches

CTD Winch: bow 1500 m, 8.18 mm diameter, heave compensation system, SWL 1.7 ton $\,$

Oceanographic winch: stern 6000 m, 12 mm diameter, Dynice synthetic rope, heave compensation system SWL 4.7 ton

GILSON Winches: 2x100 m, 16 mm diameter, SWL 6 ton

Trawl winches: 2x3000 m, 24 mm diameter, 270 kW / 25 ton

















